

Multiple solutions for a degenerate elliptic equation involving sublinear terms at infinity [☆]

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Abstract

Some multiplicity results are presented for the eigenvalue problem

$$\begin{cases} -\operatorname{div}(|x|^{-2a}\nabla u) = \lambda|x|^{-2b}f(u) + \mu|x|^{-2c}g(u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (\mathcal{P}_{\lambda,\mu})$$

where $\Omega \subset \mathbb{R}^n$ ($n \geq 3$) is an open bounded domain with smooth boundary, $0 \in \Omega$, $0 < a < \frac{n-2}{2}$, $a \leq b$, $c < a + 1$, and $f: \mathbb{R} \rightarrow \mathbb{R}$ is sublinear at infinity and superlinear at the origin. Various cases are treated depending on the behaviour of the nonlinear term g .

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1. Introduction and main results

We consider the eigenvalue problem

$$\begin{cases} -\operatorname{div}(|x|^{-2a}\nabla u) = \lambda|x|^{-2b}f(u(x)) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (\mathcal{P}_\lambda)$$

where $\Omega \subset \mathbb{R}^n$ ($n \geq 3$) is an open bounded domain with smooth boundary, $0 \in \Omega$, $0 < a < \frac{n-2}{2}$, $a \leq b < a + 1$, and $\lambda \in \mathbb{R}$ is a parameter.

Equations like (\mathcal{P}_λ) are introduced as model for several physical phenomena related to equilibrium of anisotropic media, see [6]. Due to this fact, problem (\mathcal{P}_λ) has been widely studied by several authors, see [1–3,7,13] and references therein. Usually, the nonlinear term $f: \mathbb{R} \rightarrow \mathbb{R}$ is considered to be *superlinear at infinity* or simply, $f(s) = |s|^{\theta-2}s$

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with $\theta > 2$. The common assumption in these papers is the well-known Ambrosetti–Rabinowitz condition: denoting by $F(s) = \int_0^s f(t) dt$, there exist $s_0 > 0$ and $\theta > 2$ such that

$$0 < \theta F(s) \leq sf(s), \quad \forall s \in \mathbb{R}, |s| \geq s_0. \quad (\text{AR})$$

A simple computation shows that (AR) implies

$$|f(s)| \geq c|s|^{\theta-1}, \quad \forall s \in \mathbb{R}, |s| \geq s_0, \quad (\text{AR}')$$

with $c > 0$, i.e., f is superlinear at infinity.

Our aim is to handle the counterpart of the above case, i.e., when $f : \mathbb{R} \rightarrow \mathbb{R}$ is *sublinear at infinity*. More precisely, we assume:

$$(f_1) \quad \lim_{|s| \rightarrow \infty} \frac{f(s)}{s} = 0.$$

The presence of the parameter $\lambda \in \mathbb{R}$ is essential in our problem; indeed, if beside of (f_1) , the nonlinear term f is uniformly Lipschitz (with Lipschitz constant $L > 0$), then problem (\mathcal{P}_λ) has only the trivial solution whenever $|\lambda| < (LC_{2,2b}^2)^{-1}$; the constant $C_{2,2b} > 0$ is introduced after relation (3).

In order to state our main results, we introduce the weighted Sobolev space $\mathcal{D}_a^{1,2}(\Omega)$ where the solutions of (\mathcal{P}_λ) are going to be sought, which is the completion of $\mathcal{C}_0^\infty(\Omega)$ with respect to the norm

$$\|u\|_a = \left(\int_{\Omega} |x|^{-2a} |\nabla u|^2 dx \right)^{1/2}.$$

Beside of (f_1) , we assume

$$(f_2) \quad \lim_{s \rightarrow 0} \frac{f(s)}{s} = 0 \text{ (superlinearity at zero);}$$

$$(f_3) \quad \sup_{s \in \mathbb{R}} F(s) > 0.$$

Theorem 1.1. *Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a continuous function which satisfies (f_1) , (f_2) and (f_3) . Then, there exist an open interval $\Lambda \subset (0, \infty)$ and a constant $v > 0$ such that for every $\lambda \in \Lambda$ problem (\mathcal{P}_λ) has at least two nontrivial weak solutions in $\mathcal{D}_a^{1,2}(\Omega)$ whose $\|\cdot\|_a$ -norms are less than v .*

Now, we consider the perturbation of the problem (\mathcal{P}_λ) in the form

$$\begin{cases} -\operatorname{div}(|x|^{-2a} \nabla u) = \lambda |x|^{-2b} f(u) + \mu |x|^{-2c} g(u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (\mathcal{P}_{\lambda,\mu})$$

where $0 < a < \frac{n-2}{2}$, $a \leq b$, $c < a + 1$ and for the continuous function $g : \mathbb{R} \rightarrow \mathbb{R}$ we introduce the hypotheses:

$$(g_1) \quad \text{there exist } p \in (2, 2_{a,c}^*) \text{ with } 2_{a,c}^* = \min\left\{\frac{2n}{n-2}, \frac{2(n-2c)}{n-2(a+1)}\right\} \text{ and } c_g > 0 \text{ such that } |g(s)| \leq c_g(1 + |s|^{p-1}) \text{ for every } s \in \mathbb{R};$$

$$(g_2) \quad \lim_{|s| \rightarrow \infty} \frac{|g(s)|}{|s|} = l < +\infty \text{ (asymptotically linear at infinity).}$$

It is clear that (g_2) implies (g_1) .

Theorem 1.2. *Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a continuous function which satisfies the conditions (f_1) , (f_2) , (f_3) . Then, there exists a nondegenerate compact interval $A \subset [0, \infty)$ with the following properties:*

- (i) *there exists a number $v_1 > 0$ such that for every $\lambda \in A$ and every continuous function $g : \mathbb{R} \rightarrow \mathbb{R}$ verifying (g_1) , there exists $\delta_1 > 0$ with the property that for each $\mu \in (0, \delta_1)$ the problem $(\mathcal{P}_{\lambda,\mu})$ has at least two distinct weak solutions whose $\|\cdot\|_a$ -norms are less than v_1 ;*
- (ii) *there exists a number $v_2 > 0$ such that for every $\lambda \in A$ and every continuous function $g : \mathbb{R} \rightarrow \mathbb{R}$ verifying (g_2) , there exists $\delta_2 > 0$ with the property that for each $\mu \in (0, \delta_2)$ the problem $(\mathcal{P}_{\lambda,\mu})$ has at least three distinct weak solutions whose $\|\cdot\|_a$ -norms are less than v_2 .*

It is worth to notice that problem $(\mathcal{P}_{\lambda,\mu})$ may be viewed in particular as a degenerate elliptic problem involving concave–convex nonlinearities whenever (g_1) holds; indeed, f has a sublinear growth at infinity, while g can be superlinear (and subcritical) at infinity.

The main ingredient for the proof of Theorem 1.1 is a recent critical point result due to Bonanno [4] which is actually a refinement of a result of Ricceri [9,10]. In the proof of Theorem 1.2 we use a recent result of Ricceri [11] and a version of the mountain pass theorem due to Pucci and Serrin [8].

2. Preliminaries

The starting point of the variational approach to problems (\mathcal{P}_λ) and $(\mathcal{P}_{\lambda,\mu})$ is the weighted Sobolev–Hardy inequality due to Caffarelli, Kohn, Nirenberg [5]: for all $u \in C_0^\infty(\mathbb{R}^n)$, there is a constant $K_{a,b} > 0$ such that

$$\left(\int_{\mathbb{R}^n} |x|^{-bq} |u|^q dx \right)^{2/q} \leq K_{a,b} \int_{\mathbb{R}^n} |x|^{-2a} |\nabla u|^2 dx, \tag{1}$$

where

$$-\infty < a < \frac{n-2}{2}, \quad a \leq b < a+1, \quad q = 2^*(a,b) = \frac{2n}{n-2d}, \quad d = 1+a-b.$$

From the boundedness of Ω and standard approximations argument, it is easy to see that (1) holds on $\mathcal{D}_a^{1,2}(\Omega)$; more precisely, for every

$$1 \leq r \leq \frac{2n}{n-2} \quad \text{and} \quad \frac{\alpha}{r} \leq (1+a) + n\left(\frac{1}{r} - \frac{1}{2}\right), \tag{2}$$

we have

$$\left(\int_{\Omega} |x|^{-\alpha} |u|^r dx \right)^{2/r} \leq C \int_{\Omega} |x|^{-2a} |\nabla u|^2 dx, \quad u \in \mathcal{D}_a^{1,2}(\Omega),$$

that is, the embedding $\mathcal{D}_a^{1,2}(\Omega) \hookrightarrow L^r(\Omega; |x|^{-\alpha})$ is continuous, where $L^r(\Omega; |x|^{-\alpha})$ is the weighted L^r -space with the norm

$$\|u\|_{r,\alpha} = \|u\|_{L^r(\Omega; |x|^{-\alpha})} = \left(\int_{\Omega} |x|^{-\alpha} |u|^r dx \right)^{1/r}. \tag{3}$$

We denote by $C_{r,\alpha} > 0$ the best Sobolev constant of the embedding $\mathcal{D}_a^{1,2}(\Omega) \hookrightarrow L^r(\Omega; |x|^{-\alpha})$.

The following version of the Rellich–Kondrachov compactness theorem can be stated, see Xuan [12,13].

Lemma A. *Suppose that $\Omega \subset \mathbb{R}^n$ is an open bounded domain with C^1 boundary and $0 \in \Omega, n \geq 3, -\infty < a < \frac{n-2}{2}$. The embedding $\mathcal{D}_a^{1,2}(\Omega) \hookrightarrow L^r(\Omega; |x|^{-\alpha})$ is compact if $1 \leq r < \frac{2n}{n-2}$ and $\alpha < (1+a)r + n(1 - \frac{r}{2})$.*

First, we associate the energy functional $\mathcal{E}_\lambda : \mathcal{D}_a^{1,2}(\Omega) \rightarrow \mathbb{R}$ to problem (\mathcal{P}_λ) , given by

$$\mathcal{E}_\lambda(u) = \frac{1}{2} \|u\|_a^2 - \lambda \mathcal{F}(u), \quad u \in \mathcal{D}_a^{1,2}(\Omega),$$

where $\mathcal{F}(u) = \int_{\Omega} |x|^{-2b} F(u(x)) dx$ and $F(s) = \int_0^s f(t) dt$.

Proposition 2.1. *Assume (f_1) and (f_2) hold. Then, for every $\lambda \in \mathbb{R}$ the functional \mathcal{E}_λ is well defined, of class C^1 on $\mathcal{D}_a^{1,2}(\Omega)$, sequentially weakly lower semicontinuous, and coercive. Moreover, every critical point of \mathcal{E}_λ is a weak solution of (\mathcal{P}_λ) .*

Proof. Fix $\lambda \in \mathbb{R}$. Combining (f_1) and (f_2) , there exists $M > 0$ such that

$$|f(s)| \leq M(1 + |s|) \quad \text{for all } s \in \mathbb{R}. \tag{4}$$

Then, for every $u \in \mathcal{D}_a^{1,2}(\Omega)$, we have

$$|\mathcal{F}(u)| \leq M(C_{1,2b}\|u\|_a + C_{2,2b}^2\|u\|_a^2) < \infty. \tag{5}$$

Note that the pairs $r = 1, \alpha = 2b$ and $r = 2, \alpha = 2b$ verify relation (2). Consequently, \mathcal{E}_λ is well defined.

One can see in a standard way that \mathcal{E}_λ is of class C^1 on $\mathcal{D}_a^{1,2}(\Omega)$ and every critical point of \mathcal{E}_λ is a weak solution of (\mathcal{P}_λ) .

We prove that \mathcal{F} is sequential weak continuous which clearly implies the sequential weak lower semicontinuity of \mathcal{E}_λ . To do this, we argue by contradiction; let $\{u_k\} \subset \mathcal{D}_a^{1,2}(\Omega)$ be a sequence which converges weakly to $u \in \mathcal{D}_a^{1,2}(\Omega)$ but $\{\mathcal{F}(u_k)\}$ does not converge to $\mathcal{F}(u)$ as $k \rightarrow \infty$. Therefore, up to a subsequence, one can find a number $\varepsilon_0 > 0$ such that

$$0 < \varepsilon_0 \leq |\mathcal{F}(u_k) - \mathcal{F}(u)| \quad \text{for every } k \in \mathbb{N},$$

and $\{u_k\}$ converges strongly to u in $L^1(\Omega; |x|^{-2b}) \cap L^2(\Omega; |x|^{-2b})$. Here, the pairs $r = 1, \alpha = 2b$, and $r = 2, \alpha = 2b$ verify relations from Lemma A. Using Hölder inequality and (4), for every $k \in \mathbb{N}$ one has $0 < \theta_k < 1$ such that

$$\begin{aligned} 0 < \varepsilon_0 \leq |\mathcal{F}(u_k) - \mathcal{F}(u)| &\leq \int_{\Omega} |x|^{-2b} |f(u + \theta_k(u_k - u))| |u_k - u| dx \\ &\leq M(\|u_k - u\|_{1,2b} + \|u_k + \theta_k(u_k - u)\|_{2,2b} \|u_k - u\|_{2,2b}). \end{aligned}$$

Since $\{u_k\}$ converges strongly to u in $L^1(\Omega; |x|^{-2b}) \cap L^2(\Omega; |x|^{-2b})$, both terms in the right-hand side tend to 0 as $k \rightarrow \infty$, contradicting $\varepsilon_0 > 0$.

We prove now that \mathcal{E}_λ is coercive. By (f_1) there exists $\delta_0 = \delta(\lambda) > 0$ such that

$$|f(s)| \leq C_{2,2b}^{-2} (1 + |\lambda|)^{-1} |s| \quad \text{for every } |s| \geq \delta_0.$$

Integrating the above inequality we get that

$$|F(s)| \leq \frac{1}{2} C_{2,2b}^{-2} (1 + |\lambda|)^{-1} |s|^2 + \max_{|t| \leq \delta_0} |f(t)| |s| \quad \text{for every } s \in \mathbb{R}.$$

Thus, for every $u \in \mathcal{D}_a^{1,2}(\Omega)$, we have

$$|\mathcal{F}(u)| \leq \frac{1}{2} (1 + |\lambda|)^{-1} \|u\|_a^2 + C_{1,2b} \max_{|t| \leq \delta_0} |f(t)| \|u\|_a. \tag{6}$$

Using (6), we obtain the inequality

$$\mathcal{E}_\lambda(u) \geq \frac{1}{2} \|u\|_a^2 - |\lambda| |\mathcal{F}(u)| \geq \frac{1}{2(1 + |\lambda|)} \|u\|_a^2 - |\lambda| C_{1,2b} \max_{|t| \leq \delta_0} |f(t)| \|u\|_a.$$

Consequently, if $\|u\|_a \rightarrow \infty$ then $\mathcal{E}_\lambda(u) \rightarrow \infty$ as well, i.e., \mathcal{E}_λ is coercive. \square

3. Proof of Theorem 1.1

Throughout of this section, we assume that the assumptions of Theorem 1.1 are fulfilled. First, we prove two lemmas.

Lemma 3.1. $\lim_{\rho \rightarrow 0^+} \frac{\sup\{\mathcal{F}(u): \|u\|_a^2 < 2\rho\}}{\rho} = 0.$

Proof. Due to (f_2) , for an arbitrary small $\varepsilon > 0$, there exists $\delta = \delta(\varepsilon) > 0$ such that

$$|f(s)| < \frac{\varepsilon}{2} C_{2,2b}^{-2} |s| \quad \text{for every } |s| < \delta.$$

Combining the above inequality with (4), we obtain

$$|F(s)| \leq \varepsilon C_{2,2b}^{-2} |s|^2 + K(\delta) |s|^q \quad \text{for every } s \in \mathbb{R}, \tag{7}$$

where $q \in (2, \min\{\frac{2n}{n-2}, \frac{2(n-2b)}{n-2(a+1)}\})$ is fixed and $K(\delta) > 0$ does not depend on s .

From (7) we get

$$\mathcal{F}(u) \leq \varepsilon C_{2,2b}^{-2} \int_{\Omega} |x|^{-2b} |u|^2 dx + K(\delta) \int_{\Omega} |x|^{-2b} |u|^q dx \leq \varepsilon \|u\|_a^2 + K(\delta) C_{q,2b}^q \|u\|_a^q.$$

From the above relation we obtain that

$$\sup\{\mathcal{F}(u): \|u\|_a^2 < 2\rho\} \leq 2\varepsilon\rho + K(\delta) C_{q,2b}^q (2\rho)^{\frac{q}{2}}.$$

Because $q > 2$ and $\varepsilon > 0$ is arbitrarily, we obtain

$$\lim_{\rho \rightarrow 0^+} \frac{\sup\{\mathcal{F}(u): \|u\|_a^2 < 2\rho\}}{\rho} = 0. \quad \square$$

Lemma 3.2. For every $\lambda \in \mathbb{R}$ the functional \mathcal{E}_λ satisfies the usual (PS)-condition.

Proof. Let $\{u_k\} \subset \mathcal{D}_a^{1,2}(\Omega)$ be a (PS)-sequence, i.e., $\{\mathcal{E}_\lambda(u_k)\}$ is bounded and $\mathcal{E}'_\lambda(u_k) \rightarrow 0$ in $(\mathcal{D}_a^{1,2}(\Omega))^*$ as $k \rightarrow \infty$. Since the function \mathcal{E}_λ is coercive, it follows that the sequence $\{u_k\}$ is bounded in $\mathcal{D}_a^{1,2}(\Omega)$. Up to a subsequence, we may suppose that $u_k \rightarrow u$ weakly in $\mathcal{D}_a^{1,2}(\Omega)$, and $u_k \rightarrow u$ strongly in $L^1(\Omega; |x|^{-2b}) \cap L^2(\Omega; |x|^{-2b})$ for some $u \in \mathcal{D}_a^{1,2}(\Omega)$, see Lemma A. On the other hand, we have

$$\|u_k - u\|_a^2 = \mathcal{E}'_\lambda(u_k)(u_k - u) + \mathcal{E}'_\lambda(u)(u - u_k) + \lambda \int_{\Omega} |x|^{-2b} [f(u_k(x)) - f(u(x))](u_k(x) - u(x)) dx.$$

It is clear the first two terms from the last expression tend to 0, while by means of (4) and Hölder’s inequality, one has

$$\begin{aligned} & \int_{\Omega} |x|^{-2b} |f(u_k(x)) - f(u(x))| |u_k(x) - u(x)| dx \\ & \leq M [2\|u_k - u\|_{1,2b} + (\|u_k\|_{2,2b} + \|u\|_{2,2b}) \|u_k - u\|_{2,2b}] \rightarrow 0 \end{aligned}$$

as $k \rightarrow \infty$. Thus, we have $\|u_k - u\|_a \rightarrow 0$ as $k \rightarrow \infty$.

Let $s_0 \in \mathbb{R}$ such that $F(s_0) > 0$, see (f₃). Here and in the sequel, let $x_0 \in \Omega$ and $r_0 > 0$ so small such that $|x_0| > r_0$ and $B(x_0, r_0) \subset \Omega$. Then, clearly, $B(x_0, r_0) \subset \Omega \setminus \{0\}$. As usual $B(x_0, r_0)$ denotes the n -dimensional open ball with center in x_0 and radius $r_0 > 0$.

For $\sigma \in (0, 1)$ we define

$$u_\sigma(x) = \begin{cases} 0, & \text{if } x \in \Omega \setminus B(x_0, r_0); \\ \frac{s_0}{1-\sigma} - \frac{s_0}{r_0(1-\sigma)} |x - x_0|, & \text{if } x \in B(x_0, r_0) \setminus B(x_0, \sigma r_0); \\ s_0, & \text{if } x \in B(x_0, \sigma r_0). \end{cases} \quad (8)$$

It is clear that $u_\sigma \in \mathcal{D}_a^{1,2}(\Omega)$. Moreover, one has

$$\|u_\sigma\|_a^2 \geq s_0^2 (|x_0| + r_0)^{-2a} (1 - \sigma)^{-2} (1 - \sigma^n) \omega_n r_0^{n-2} \quad (9)$$

and

$$\mathcal{F}(u_\sigma) \geq K_{s_0, x_0, r_0}(\sigma), \quad (10)$$

where

$$K_{s_0, x_0, r_0}(\sigma) = \left[F(s_0) (|x_0| + r_0)^{-2b} \sigma^n - \max_{|t| \leq |s_0|} |F(t)| (|x_0| - r_0)^{-2b} (1 - \sigma^n) \right] \omega_n r_0^n$$

and ω_n denotes the volume of the n -dimensional unit ball. For σ close enough to 1, the right-hand side of (10) becomes strictly positive; choose such a number, say σ_0 .

Now, we recall a recent result from critical point theory, due to Ricceri [9,10], and Bonanno [4].

Theorem R1. (See [4, Theorem 2.1].) Let X be a separable and reflexive real Banach space, and let $\mathcal{A}, \mathcal{F} : X \rightarrow \mathbb{R}$ be two continuously Gâteaux differentiable functionals. Assume that there exists $x_0 \in X$ such that $\mathcal{A}(x_0) = \mathcal{F}(x_0) = 0$ and $\mathcal{A}(x) \geq 0$ for every $x \in X$ and that there exist $x_1 \in X, \rho > 0$ such that

- (i) $\rho < \mathcal{A}(x_1)$;
- (ii) $\sup_{\mathcal{A}(x) < \rho} \mathcal{F}(x) < \rho \frac{\mathcal{F}(x_1)}{\mathcal{A}(x_1)}$.

Further, put

$$\bar{a} = \frac{\zeta \rho}{\rho \frac{\mathcal{F}(x_1)}{\mathcal{A}(x_1)} - \sup_{\mathcal{A}(x) < \rho} \mathcal{F}(x)},$$

with $\zeta > 1$, assume that the functional $\mathcal{A} - \lambda \mathcal{F}$ is sequentially weakly lower semicontinuous, satisfies the Palais–Smale condition and

- (iii) $\lim_{\|x\| \rightarrow \infty} (\mathcal{A}(x) - \lambda \mathcal{F}(x)) = \infty$ for every $\lambda \in [0, \bar{a}]$.

Then there is an open interval $\Lambda \subset [0, \bar{a}]$ and a number $\nu > 0$ such that for each $\lambda \in \Lambda$, the equation $\mathcal{A}'(x) - \lambda \mathcal{F}'(x) = 0$ admits at least three distinct solutions in X having norm less than ν .

Proof of Theorem 1.1 completed. On account of Lemma 3.1, (9) and (10), we may choose $\rho_0 > 0$ so small such that

$$2\rho_0 < \|u_{\sigma_0}\|_a^2, \quad \frac{\sup\{\mathcal{F}(u) : \|u\|_a^2 < 2\rho_0\}}{\rho_0} < \frac{2K_{s_0, x_0, r_0}(\sigma_0)}{\|u_{\sigma_0}\|_a^2}.$$

By choosing $X = \mathcal{D}_a^{1,2}(\Omega), \mathcal{A} = \frac{1}{2} \|\cdot\|_a^2, x_0 = 0, x_1 = u_{\sigma_0}$, and

$$\bar{a} = \frac{1 + \rho_0}{\frac{2\mathcal{F}(u_{\sigma_0})}{\|u_{\sigma_0}\|_a^2} - \frac{\sup\{\mathcal{F}(u) : \|u\|_a^2 < 2\rho_0\}}{\rho_0}},$$

all the hypotheses of Theorem R1 are verified, see also Proposition 2.1 and Lemma 3.2.

Thus there exist an open interval $\Lambda \subset [0, \bar{a}]$ and a number $\nu > 0$ such that for each $\lambda \in \Lambda$, the equation $\mathcal{E}'_\lambda(u) \equiv \mathcal{A}'(u) - \lambda \mathcal{F}'(u) = 0$ admits at least three distinct solutions in $\mathcal{D}_a^{1,2}(\Omega)$ having $\mathcal{D}_a^{1,2}(\Omega)$ -norm less than ν . Since one of them may be the trivial one ($f(0) = 0$, see (f_2)), we still have at least two nontrivial solutions of (\mathcal{P}_λ) with the required properties. \square

4. Proof of Theorems 1.2

Throughout of this section, we assume that the assumptions of Theorem 1.2 are fulfilled.

Let us define the function

$$\beta(t) = \sup\{\mathcal{F}(u) : \|u\|_a^2 < 2t\}, \quad t > 0.$$

Then, Lemma 3.1 yields that

$$\lim_{t \rightarrow 0^+} \frac{\beta(t)}{t} = 0. \tag{11}$$

Take the function from (8) for $\sigma_0 > 0$ fixed in the previous section; thus, $u_{\sigma_0} \in \mathcal{D}_a^{1,2}(\Omega) \setminus \{0\}$ and $\mathcal{F}(u_{\sigma_0}) > 0$. Therefore it is possible to choose a number $\eta > 0$ such that

$$0 < \eta < \mathcal{F}(u_{\sigma_0}) \frac{2}{\|u_{\sigma_0}\|_a^2}.$$

From (11) we get the existence of a number $t_0 \in (0, \|u_{\sigma_0}\|_a^2/2)$ such that $\beta(t_0) < \eta t_0$. Thus

$$\beta(t_0) < \frac{2}{\|u_{\sigma_0}\|_a^2} \mathcal{F}(u_{\sigma_0}) t_0. \tag{12}$$

Due to the choice of t_0 and using (12), we conclude that there exists $\rho_0 > 0$ such that

$$\beta(t_0) < \rho_0 < \mathcal{F}(u_{\sigma_0}) \frac{2}{\|u_{\sigma_0}\|_a^2} t_0 < \mathcal{F}(u_{\sigma_0}). \tag{13}$$

Define now the function $\mathcal{H} : \mathcal{D}_a^{1,2}(\Omega) \times \mathbb{I} \rightarrow \mathbb{R}$ by

$$\mathcal{H}(u, \lambda) = \mathcal{E}_\lambda(u) + \lambda \rho_0,$$

where $\mathbb{I} = [0, \infty)$. We prove that the following inequality holds:

$$\sup_{\lambda \in \mathbb{I}} \inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \mathcal{H}(u, \lambda) < \inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \sup_{\lambda \in \mathbb{I}} \mathcal{H}(u, \lambda). \tag{14}$$

The function

$$\lambda \in \mathbb{I} \mapsto \inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \left[\frac{1}{2} \|u\|_a^2 + \lambda(\rho_0 - \mathcal{F}(u)) \right]$$

is obviously upper semicontinuous on \mathbb{I} . It follows from (13) that

$$\lim_{\lambda \rightarrow +\infty} \inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \mathcal{H}(u, \lambda) \leq \lim_{\lambda \rightarrow +\infty} \left[\frac{1}{2} \|u_{\sigma_0}\|_a^2 + \lambda(\rho_0 - \mathcal{F}(u_{\sigma_0})) \right] = -\infty.$$

Thus we find an element $\bar{\lambda} \in \mathbb{I}$ such that

$$\sup_{\lambda \in \mathbb{I}} \inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \mathcal{H}(u, \lambda) = \inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \left[\frac{1}{2} \|u\|_a^2 + \bar{\lambda}(\rho_0 - \mathcal{F}(u)) \right]. \tag{15}$$

Since $\beta(t_0) < \rho_0$, it follows that for all $u \in \mathcal{D}_a^{1,2}(\Omega)$ with $\|u\|_a^2 < 2t_0$ we have $\mathcal{F}(u) < \rho_0$. Hence

$$t_0 \leq \inf \left\{ \frac{1}{2} \|u\|_a^2 : \mathcal{F}(u) \geq \rho_0 \right\}. \tag{16}$$

On the other hand,

$$\inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \sup_{\lambda \in \mathbb{I}} \mathcal{H}(u, \lambda) = \inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \left[\frac{1}{2} \|u\|_a^2 + \sup_{\lambda \in \mathbb{I}} (\lambda(\rho_0 - \mathcal{F}(u))) \right] = \inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \left\{ \frac{1}{2} \|u\|_a^2 : \mathcal{F}(u) \geq \rho_0 \right\}.$$

Thus inequality (16) is equivalent to

$$t_0 \leq \inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \sup_{\lambda \in \mathbb{I}} \mathcal{H}(u, \lambda). \tag{17}$$

We consider the following two cases:

(I) If $0 \leq \bar{\lambda} < \frac{t_0}{\rho_0}$, then we have that

$$\inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \left[\frac{1}{2} \|u\|_a^2 + \bar{\lambda}(\rho_0 - \mathcal{F}(u)) \right] \leq \mathcal{H}(0, \bar{\lambda}) = \bar{\lambda} \rho_0 < t_0.$$

Combining this inequality with (15) and (17) we obtain (14).

(II) If $\frac{t_0}{\rho_0} \leq \bar{\lambda}$, then from the fact that $\rho_0 < \mathcal{F}(u_{\sigma_0})$ and from (13), it follows that

$$\inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \left[\frac{1}{2} \|u\|_a^2 + \bar{\lambda}(\rho_0 - \mathcal{F}(u)) \right] \leq \frac{1}{2} \|u_{\sigma_0}\|_a^2 + \bar{\lambda}(\rho_0 - \mathcal{F}(u_{\sigma_0})) \leq \frac{1}{2} \|u_{\sigma_0}\|_a^2 + \frac{t_0}{\rho_0} (\rho_0 - \mathcal{F}(u_{\sigma_0})) < t_0,$$

which proves (14).

Now, we are in the position to apply the following result of Ricceri:

Theorem R2. (See [11, Theorem 5].) Let X be a reflexive real Banach space, $\mathbb{I} \subset \mathbb{R}$ an interval, and let $\Psi : X \times \mathbb{I} \rightarrow \mathbb{R}$ be a function such that $\Psi(x, \cdot)$ is concave on \mathbb{I} for all $x \in X$, and $\Psi(\cdot, \lambda)$ is continuous, coercive and sequentially weakly lower semicontinuous on X for all $\lambda \in \mathbb{I}$. Further, assume that

$$\sup_{\lambda \in \mathbb{I}} \inf_{x \in X} \Psi(x, \lambda) < \inf_{x \in X} \sup_{\lambda \in \mathbb{I}} \Psi(x, \lambda).$$

Then, for each $\gamma > \sup_{\lambda \in \mathbb{I}} \inf_{x \in X} \Psi(x, \lambda)$, there exists a nonempty open set $C \subset \mathbb{I}$ with the following property: For every $\lambda \in C$ and every sequentially weakly lower semicontinuous functional $\Phi : X \rightarrow \mathbb{R}$ there exists $\delta > 0$ such that, for each $\mu \in (0, \delta)$, the functional $\Psi(\cdot, \lambda) + \mu\Phi(\cdot)$ has at least two distinct local minima lying in the set $\{x \in X : \Psi(x, \lambda) < \gamma\}$.

Proof of Theorem 1.2(i) completed. We choose in Theorem R2: $X = \mathcal{D}_a^{1,2}(\Omega)$, $\mathbb{I} = [0, \infty)$ and $\Psi = \mathcal{H}$. It is clear that for each $u \in \mathcal{D}_a^{1,2}(\Omega)$ the functional $\mathcal{H}(u, \cdot)$ is concave on \mathbb{I} . Obviously $\mathcal{H}(\cdot, \lambda)$ is continuous, and it follows from Proposition 2.1 that $\mathcal{H}(\cdot, \lambda)$ is coercive and sequentially weakly lower semicontinuous on $\mathcal{D}_a^{1,2}(\Omega)$. The minimax inequality is precisely relation (14).

Assume that g satisfies (g_1) , and $a \leq c < a + 1$. We denote by

$$\mathcal{G}(u) = - \int_{\Omega} |x|^{-2c} G(u(x)) dx, \quad u \in \mathcal{D}_a^{1,2}(\Omega),$$

where $G(s) = \int_0^s g(t) dt$. The functional \mathcal{G} is well defined, of class C^1 , and sequentially weakly continuous on $\mathcal{D}_a^{1,2}(\Omega)$. The first two facts follow in a standard way; we deal only with the sequential weak continuity of \mathcal{G} . We suppose that there exists a sequence $\{u_k\} \subset \mathcal{D}_a^{1,2}(\Omega)$ which converges weakly to $u \in \mathcal{D}_a^{1,2}(\Omega)$ but $\{\mathcal{G}(u_k)\}$ does not converge to $\mathcal{G}(u)$ as $k \rightarrow \infty$. So, up to a subsequence, we can find a number $\varepsilon_0 > 0$ such that

$$0 < \varepsilon_0 \leq |\mathcal{G}(u_k) - \mathcal{G}(u)| \quad \text{for every } k \in \mathbb{N},$$

and $\{u_k\}$ converges strongly to u in $L^1(\Omega; |x|^{-2c}) \cap L^p(\Omega; |x|^{-2c})$, where $p \in (2, 2_{a,c}^*)$ is from (g_1) . Note that the pairs $r = 1, \alpha = 2c$, and $r = p, \alpha = 2c$ verify relations from Lemma A. Using Hölder inequality and (g_1) , for every $k \in \mathbb{N}$ one has $0 < \theta_k < 1$ such that

$$\begin{aligned} 0 < \varepsilon_0 &\leq |\mathcal{G}(u_k) - \mathcal{G}(u)| \\ &\leq \int_{\Omega} |x|^{-2c} |g(u + \theta_k(u_k - u))| |u_k - u| dx \\ &\leq c_g (\|u_k - u\|_{1,2c} + \|u + \theta_k(u_k - u)\|_{p,2c}^{p-1} \|u_k - u\|_{p,2c}). \end{aligned}$$

Since u_k converges strongly to u in $L^1(\Omega; |x|^{-2c}) \cap L^p(\Omega; |x|^{-2c})$, both terms in the right-hand side tend to 0 as $k \rightarrow \infty$, contradicting $\varepsilon_0 > 0$. Therefore, the functional \mathcal{G} is sequential weak continuous.

Now, for a fixed $\gamma > \sup_{\lambda \in \mathbb{I}} \inf_{u \in \mathcal{D}_a^{1,2}(\Omega)} \mathcal{H}(u, \lambda)$, Theorem R2 assures that there exists a nonempty open set $C \subset \mathbb{I}$ with the property that for every $\lambda \in C$ there exists $\delta_1 > 0$ such that for each $\mu \in (0, \delta_1)$ the function $u \mapsto \mathcal{H}(u, \lambda) + \mu\mathcal{G}(u)$ has at least two local minima $u_{\lambda,\mu}^1$ and $u_{\lambda,\mu}^2$ belonging to the set $\{u \in \mathcal{D}_a^{1,2}(\Omega) : \mathcal{H}(u, \lambda) < \gamma\}$. Therefore, the energy functional $\mathcal{E}_{\lambda,\mu}$ associated to the problem $(\mathcal{P}_{\lambda,\mu})$, which is nothing but

$$\mathcal{E}_{\lambda,\mu}(u) = \mathcal{H}(u, \lambda) + \mu\mathcal{G}(u) - \lambda\rho_0$$

has two local minima in the set $\{u \in \mathcal{D}_a^{1,2}(\Omega) : \mathcal{H}(u, \lambda) < \gamma\}$. Consequently, $u_{\lambda,\mu}^1$ and $u_{\lambda,\mu}^2$ are weak solutions for the problem $(\mathcal{P}_{\lambda,\mu})$.

Finally let $A = [c_0, c_1] \subset C$ be any non-degenerate compact interval with $c_0 > 0$. It is clear that

$$\bigcup_{\lambda \in [c_0, c_1]} \{u \in \mathcal{D}_a^{1,2}(\Omega) : \mathcal{H}(u, \lambda) \leq \gamma\} \subseteq \{u \in \mathcal{D}_a^{1,2}(\Omega) : \mathcal{H}(u, c_0) \leq \gamma\} \cup \{u \in \mathcal{D}_a^{1,2}(\Omega) : \mathcal{H}(u, c_1) \leq \gamma\}.$$

Since $\mathcal{H}(\cdot, \lambda) = \mathcal{E}_{\lambda} + \lambda\rho_0$ is coercive it follows that the set

$$S := \bigcup_{\lambda \in [c_0, c_1]} \{u \in \mathcal{D}_a^{1,2}(\Omega) : \mathcal{H}(u, \lambda) \leq \gamma\}$$

is bounded. Hence the $\|\cdot\|_a$ -norms of the local minima of $\mathcal{E}_{\lambda, \mu}$ are less or equal than v_1 , where $v_1 = \sup_{u \in S} \|u\|_a$.

Proof of Theorem 1.2(ii) completed. Since (g_2) implies (g_1) , we may consider $\lambda \in A = [c_0, c_1]$ and $\mu \in (0, \delta_1)$ from (i), i.e., the functional $\mathcal{E}_{\lambda, \mu}$ has at least two local minima $u_{\lambda, \mu}^1, u_{\lambda, \mu}^2 \in S$.

In order to establish the existence of the third solution, we prove that $\mathcal{E}_{\lambda, \mu}$ is still coercive for $\lambda \in A$ and μ small enough. Condition (g_2) implies the existence of a constant $m > 0$ such that

$$|G(s)| \leq m|s|^2 + m|s| \quad \text{for every } s \in \mathbb{R}.$$

This inequality yields that

$$|\mathcal{G}(u)| \leq mC_{2,2c}^2 \|u\|_a^2 + mC_{1,2c} \|u\|_a. \tag{18}$$

Let $\delta_2 = \min\{\delta_1, 2^{-1}m^{-1}(1 + \lambda)^{-1}C_{2,2c}^{-2}\}$ and fix $\mu \in (0, \delta_2)$. Using (6) and (18) we get that

$$\mathcal{E}_{\lambda, \mu}(u) \geq \left(\frac{1}{2(1 + \lambda)} - \mu m C_{2,2c}^2 \right) \|u\|_a^2 - \left(\lambda C_{1,2b} \max_{|t| \leq \delta_0} |f(t)| + \mu m C_{1,2c}^2 \right) \|u\|_a.$$

Due to the choice of δ_2 , it follows that the functional $\mathcal{E}_{\lambda, \mu}$ is coercive. Thus, as in Lemma 3.2, $\mathcal{E}_{\lambda, \mu}$ satisfies the (PS)-condition whenever $\lambda \in A$ and $\mu \in (0, \delta_2)$.

For $\lambda \in A$ and $\mu \in (0, \delta_2)$ fixed, let us consider the set $\Gamma_{\lambda, \mu}$ of continuous paths $w : [0, 1] \rightarrow \mathcal{D}_a^{1,2}(\Omega)$ joining $u_{\lambda, \mu}^1$ and $u_{\lambda, \mu}^2$, and define the minimax value

$$c_{\lambda, \mu} = \inf_{w \in \Gamma_{\lambda, \mu}} \max_{t \in [0, 1]} \mathcal{E}_{\lambda, \mu}(w(t)).$$

Combining [8, Theorem 1] and [8, Corollary 1], there exists a third critical point $u_{\lambda, \mu}^3 \in \mathcal{D}_a^{1,2}(\Omega)$ for $\mathcal{E}_{\lambda, \mu}$ which is different from $u_{\lambda, \mu}^1$ and $u_{\lambda, \mu}^2$ and $\mathcal{E}_{\lambda, \mu}(u_{\lambda, \mu}^3) = c_{\lambda, \mu}$.

It remains to find a norm estimate for $u_{\lambda, \mu}^3$ as we did in (i) for $u_{\lambda, \mu}^1$ and $u_{\lambda, \mu}^2$, respectively. To complete this, let us fix the path $w_0 \in \Gamma_{\mu, \lambda}$ defined by

$$w_0(t) = (1 - t)u_{\lambda, \mu}^1 + tu_{\lambda, \mu}^2 \quad \text{for all } t \in [0, 1].$$

Note that for all $t \in [0, 1]$ we have $\|w_0(t)\|_a < v_1$. Consequently, due to (5) and (18) we have

$$\begin{aligned} \mathcal{E}_{\lambda, \mu}(w_0(t)) &\leq \frac{1}{2\|w_0(t)\|_a^2} + \lambda |\mathcal{F}(w_0(t))| + \mu |\mathcal{G}(w_0(t))| \\ &\leq \frac{1}{2}v_1^2 + c_1 M C_{2,2b}^2 v_1^2 + c_1 M C_{1,2b} v_1 + \delta_1 m C_{2,2c}^2 v_1^2 + \delta_1 m C_{1,2c} v_1 =: K. \end{aligned}$$

Therefore,

$$\mathcal{E}_{\lambda, \mu}(u_{\lambda, \mu}^3) = c_{\lambda, \mu} \leq \sup_{t \in [0, 1]} \mathcal{E}_{\lambda, \mu}(w_0(t)) \leq K.$$

Now, we introduce for every $\mu \in [0, \delta_2]$ the set

$$Z_\mu = \{u \in \mathcal{D}_a^{1,2}(\Omega) : \mathcal{E}_{\lambda, \mu}(u) \leq K\}.$$

Then, for every $\lambda \in A$ and $\mu \in (0, \delta_2)$ we have

$$u_{\lambda, \mu}^3 \in Z := \bigcup_{\mu \in (0, \delta_2)} Z_\mu \subset \bigcup_{\mu \in [0, \delta_2]} Z_\mu \subset Z_0 \cup Z_{\delta_2}.$$

On the other hand, the coercivity of $\mathcal{E}_{\lambda, \mu}$ implies the boundedness of the set $Z \subset Z_0 \cup Z_{\delta_2}$. Therefore, there exists $\tilde{v} > 0$ such that $\|u\|_a < \tilde{v}$ for all $u \in Z$. Thus $\|u_{\lambda, \mu}^i\|_a < \max\{v_1, \tilde{v}\} =: v_2$ ($i \in \{1, 2, 3\}$). This concludes the proof. \square

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